Abstract Interpretation: a methodology for the rapid development of provably correct static analyzers

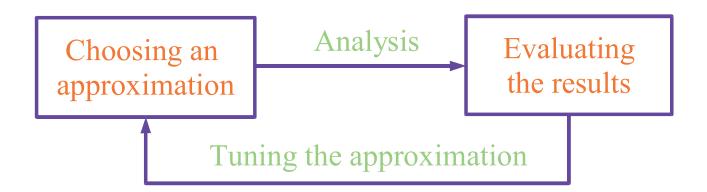
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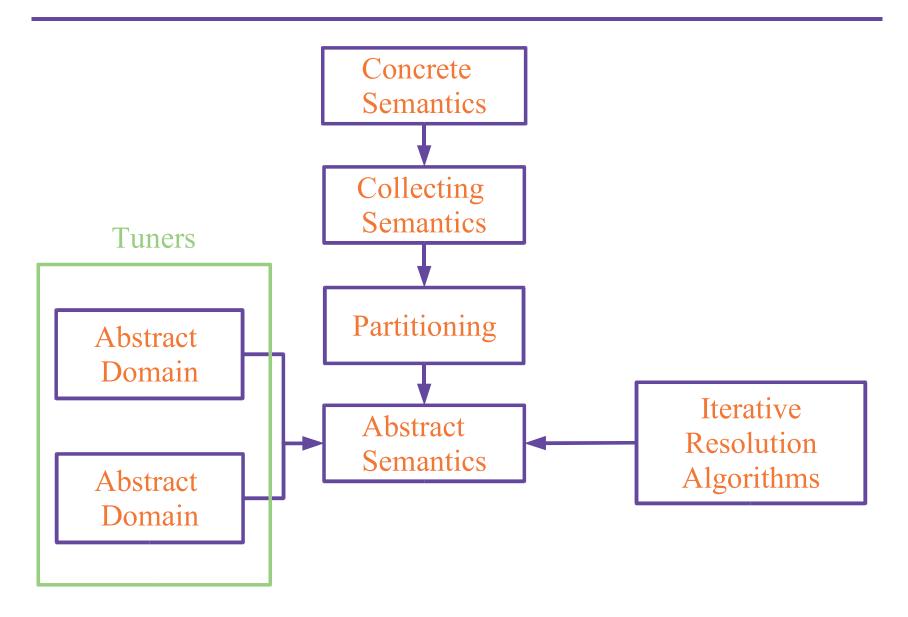
Static analysis in real life

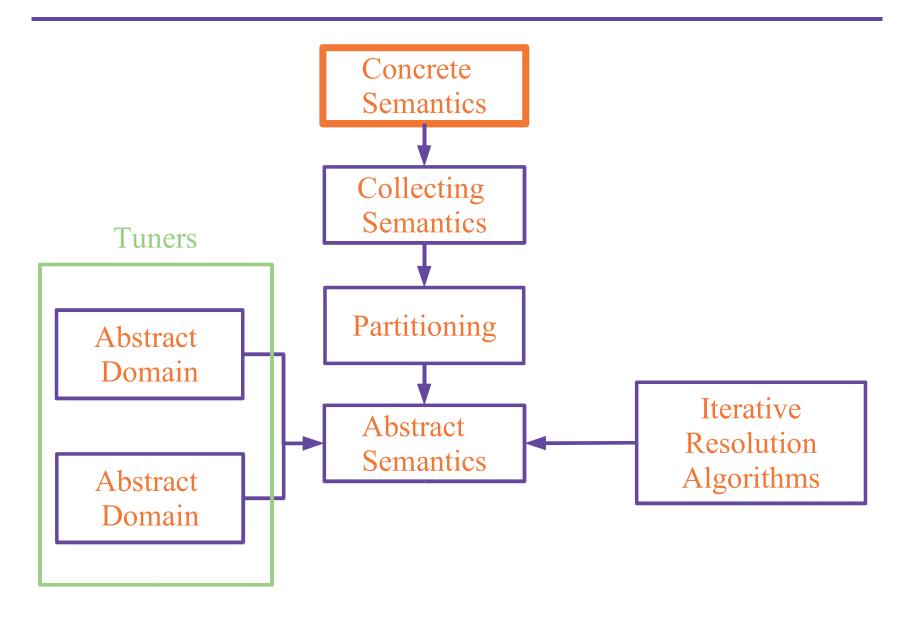
- Undecidable problem: automatic program verification ⇒ loops
- Approximation for decidability: false positives
- Tradeoff precision/efficiency
- The approximation should be tunable:



Abstract Interpretation

- + A general methodology for building static analyzers
- + Provides generic algorithms
- + Approximation and resolution are separated: the analyzers are tunable by construction
- + The soundness proof goes along with the analyzer design
- Scalability is difficult to achieve





Concrete semantics

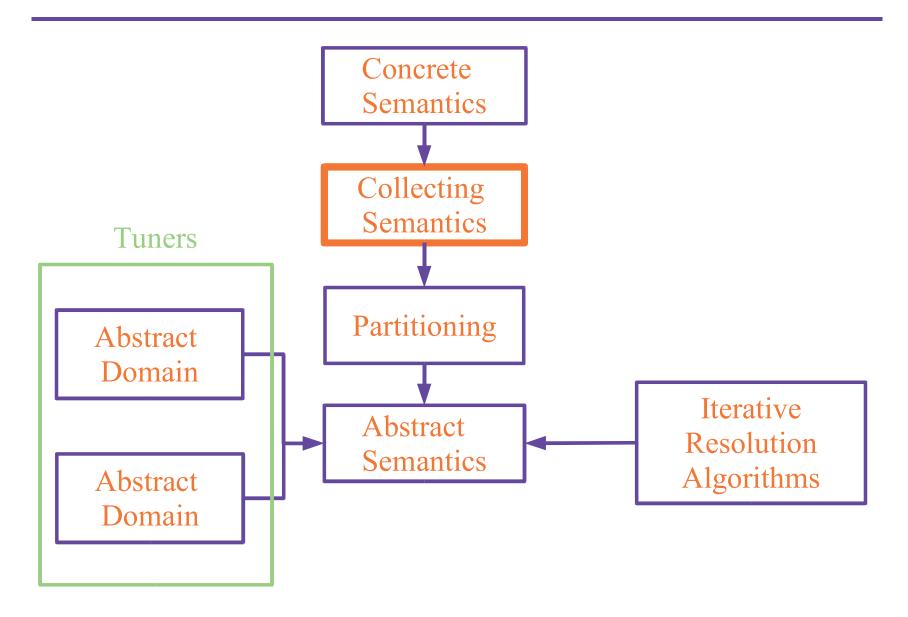
Small-step operational semantics: (Σ, \rightarrow)

$$S = \langle program point, env \rangle$$

$$s \rightarrow s'$$

Example:

```
1: n = 0;
                                2: while n < 1000 do
                                3: n = n + 1;
                                4: end
                                5: exit
\langle 1, n \Rightarrow \Omega \rangle \rightarrow \langle 2, n \Rightarrow 0 \rangle \rightarrow \langle 3, n \Rightarrow 0 \rangle \rightarrow \langle 4, n \Rightarrow 1 \rangle
                        \rightarrow \langle 2, n \Rightarrow 1 \rangle \rightarrow ... \rightarrow \langle 5, n \Rightarrow 1000 \rangle
```



Collecting semantics

The first abstraction step. It defines the observable behaviors of programs:

- Sets of states (e.g. range of variables)
- Sets of finite traces (e.g. computational dependencies)
- Sets of finite and infinite traces (e.g. termination properties)

State properties

The set of descendants of the initial state s_0 :

$$\mathbf{S} = \{ \mathbf{S} \mid \mathbf{S}_0 \to \dots \to \mathbf{S} \}$$

Theorem:
$$\mathbf{F}: (\wp(\Sigma), \subseteq) \to (\wp(\Sigma), \subseteq)$$

$$\mathbf{F}(S) = \{s_0\} \cup \{s' \mid \exists s \in S : s \to s'\}$$

$$S = lfp F$$

Example

```
1: n = 0;

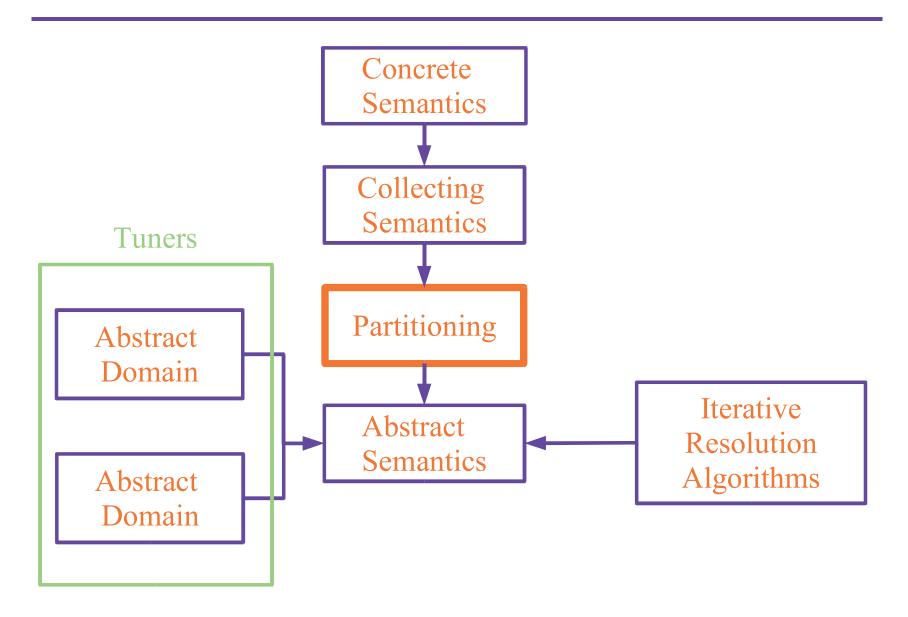
2: while n < 1000 do

3: n = n + 1;

4: end

5: exit
```

```
S = \{ \langle 1, n \Rightarrow \Omega \rangle, \langle 2, n \Rightarrow 0 \rangle, \langle 3, n \Rightarrow 0 \rangle, \langle 4, n \Rightarrow 1 \rangle, \\ \langle 2, n \Rightarrow 1 \rangle, ..., \langle 5, n \Rightarrow 1000 \rangle \}
```



Partitioning

We partition the set Σ of states w.r.t. program points:

•
$$\Sigma = \Sigma_1 \oplus \Sigma_2 \oplus ... \oplus \Sigma_n$$

- $F(S_1, ..., S_n)_i = \{s' \in S_i \mid \exists j \exists s \in S_j : s \to s'\}$
- Control-flow graph: $(\mathbf{P}, \rightarrow)$
- $\mathbf{F}(S_1, ..., S_n)_i = \{\langle i, \epsilon' \rangle \mid \exists j \rightarrow i : \langle j, \epsilon \rangle \rightarrow \langle i, \epsilon' \rangle \}$

Semantic equations

- $i \rightarrow j$: operation op
- Notation: E_i = set of environments at program point i
- $[\mathbf{op}]_{\varepsilon} = \text{semantics of } \mathbf{op}$
- System of semantic equations:

$$E_{i} = U \{ [op]E_{j} | j \rightarrow i : op \}$$

• Solution of the system = S = lfp F

Example

```
1: n = 0;

2: while n < 1000 do

3: n = n + 1;

4: end

5: exit
```

$$E_{1} = \{\mathbf{n} \Rightarrow \mathbf{\Omega}\}$$

$$E_{2} = [\mathbf{n} = \mathbf{0}]E_{1} \cup E_{4}$$

$$E_{3} = E_{2} \cap]-\infty, 999]$$

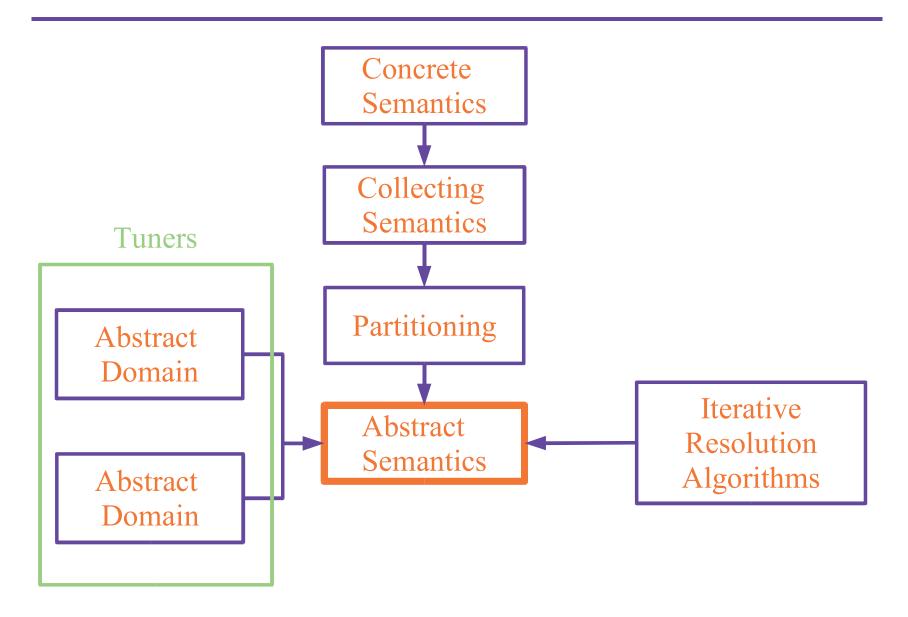
$$E_{4} = [\mathbf{n} = \mathbf{n} + \mathbf{1}]E_{3}$$

$$E_{5} = E_{2} \cap [1000, +\infty[$$

Other kinds of partitioning

In the case of collecting semantics of traces:

- Partitioning w.r.t. procedure calls: context sensitivity
- Partitioning w.r.t. executions paths in a procedure:
 path sensitivity
- Dynamic partitioning (Bourdoncle)



Approximation

Problem: Compute a sound approximation S# of S

$$s \subseteq s^{\#}$$

Solution: Galois connections

Galois connection

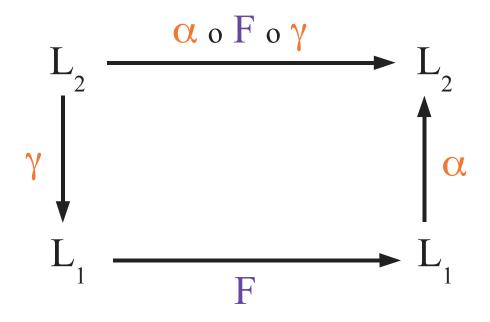
$$L_1, L_2$$
 two lattices

$$(L_1, \subseteq) \qquad \qquad \qquad (L_2, \leq)$$

$$\alpha$$

- $\forall x \forall y : \alpha(x) \le y \iff x \subseteq \gamma(y)$
- $\forall x \forall y : x \subseteq \gamma \circ \alpha(x) \& \alpha \circ \gamma(y) \le y$

Fixpoint approximation



Theorem:

$$lfp F \subseteq_{\gamma} (lfp \alpha \circ F \circ \gamma)$$

Abstracting the collecting semantics

• Find a Galois connection:

$$(\wp(\Sigma),\subseteq)$$
 $\stackrel{\gamma}{\longleftarrow}(\Sigma^{\#},\leq)$

• Find a function: $\alpha \circ \mathbf{F} \circ \gamma \leq \mathbf{F}^{\#}$

Partitioning \Rightarrow Abstract sets of environments

Abstract algebra

- Notation: E the set of all environments
- Galois connection:

$$(\wp(\mathbf{E}),\subseteq)$$
 $\stackrel{\gamma}{\longleftarrow}(\mathbf{E}^{\#},\leq)$

- \cup , \cap approximated by $\cup^{\#}$, $\cap^{\#}$
- [op] approximated by [op]#

$$\alpha \circ [op] \circ \gamma \leq [op]^{\#}$$

Abstract semantic equations

```
1: n = 0;

2: while n < 1000 do

3: n = n + 1;

4: end

5: exit
```

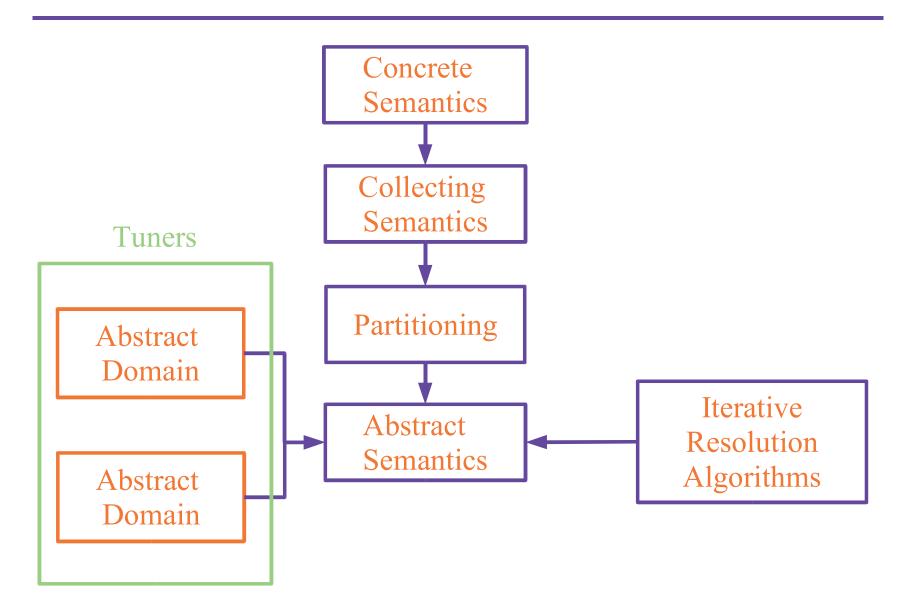
$$E_{1}^{\#} = \alpha (\{n \Rightarrow \Omega\})$$

$$E_{2}^{\#} = [\mathbf{n} = \mathbf{0}]^{\#} E_{1}^{\#} \cup^{\#} E_{4}^{\#}$$

$$E_{3}^{\#} = E_{2}^{\#} \cap^{\#} \alpha (]-\infty, 999])$$

$$E_{4}^{\#} = [\mathbf{n} = \mathbf{n} + \mathbf{1}]^{\#} E_{3}^{\#}$$

$$E_{5}^{\#} = E_{2}^{\#} \cap^{\#} \alpha ([1000, +\infty[)$$



Abstract domains

Environment: $x \Rightarrow v, y \Rightarrow w, ...$

Various kinds of approximations:

• Intervals (nonrelational):

$$x \Rightarrow [a, b], y \Rightarrow [a', b'], ...$$

• Polyhedra (relational):

$$x + y - 2z \le 10, ...$$

• Difference-bound matrices (weakly relational):

$$y - x \le 5, z - y \le 10, ...$$

Example: intervals

```
1: n = 0;

2: while n < 1000 do

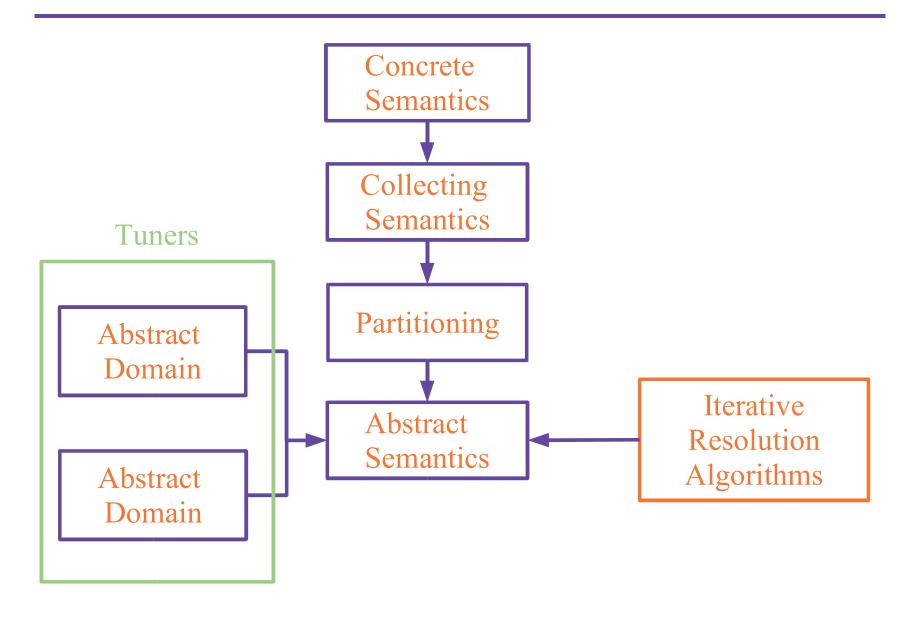
3: n = n + 1;

4: end

5: exit
```

- Iteration 1: $E_{2}^{\#} = [0, 0]$
- Iteration 2: $E_2^{\#} = [0, 1]$
- Iteration 3: $E_2^{\#} = [0, 2]$
- Iteration 4: $E_2^{\#} = [0, 3]$

•



Widening operator

Lattice (L, \leq): $\nabla : L \times L \rightarrow L$

• Abstract union operator:

$$\forall x \forall y : x \le x \nabla y \& y \le x \nabla y$$

• Enforces convergence: $(x_n)_{n \ge 0}$

$$\begin{cases} y_0 = x_0 \\ y_{n+1} = y_n \nabla x_{n+1} \end{cases}$$

 $(y_n)_{n>0}$ is ultimately stationary

Widening of intervals

$$[a, b] \nabla [a', b']$$

- If $a \le a'$ then a else $-\infty$
- If $b' \le b$ then b else $+\infty$
- → Open unstable bounds (jump over the fixpoint)

Iteration with widening

```
1: n = 0;

2: while n < 1000 do

3: n = n + 1;

4: end

5: exit
```

$$(E_{2}^{\#})_{n+1} = (E_{2}^{\#})_{n} \nabla ([\mathbf{n} = \mathbf{0}]^{\#}(E_{1}^{\#})_{n} \cup^{\#}(E_{4}^{\#})_{n})$$

Iteration 1 (union): $E_2^{\#} = [0, 0]$

Iteration 2 (union): $E_2^{\#} = [0, 1]$

Iteration 3 (widening): $E_2^{\#} = [0, +\infty] \Rightarrow \text{stable}$

Imprecision at loop exit

```
1: n = 0;

2: while n < 1000 do

3: n = n + 1;

4: end

5: exit; t[n] = 0;
```

•
$$E_5^{\#} = [1000, +\infty[$$

• The information is present in the equations

Narrowing operator

Lattice (L, \leq) : $\Delta : L \times L \rightarrow L$

• Abstract intersection operator:

$$\forall x \forall y : x \cap y \le x \Delta y$$

• Enforces convergence: $(x_n)_{n \ge 0}$

$$\begin{cases} y_0 = x_0 \\ y_{n+1} = y_n \Delta x_{n+1} \end{cases}$$

 $(y_n)_{n>0}$ is ultimately stationary

Narrowing of intervals

$$[a, b] \Delta [a', b']$$

- If $a = -\infty$ then a' else a
- If $b = +\infty$ then b' else b
- Refine open bounds

Iteration with narrowing

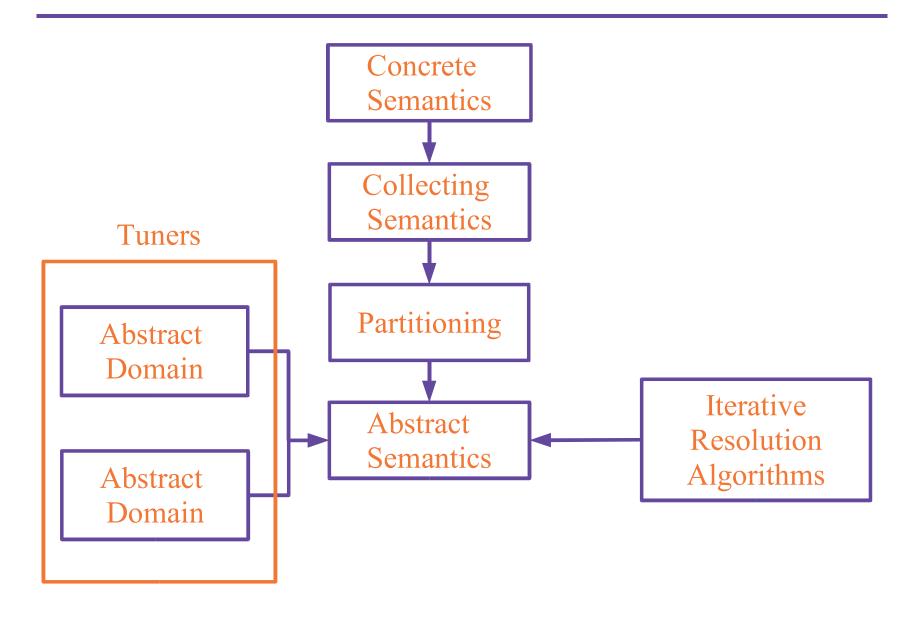
```
1: n = 0;
2: while n < 1000 do
3: n = n + 1;
4: end
5: exit; t[n] = 0;</pre>
```

$$(E_{2}^{\#})_{n+1} = (E_{2}^{\#})_{n} \Delta ([n = 0]^{\#}(E_{1}^{\#})_{n} \cup^{\#}(E_{4}^{\#})_{n})$$

Beginning of iteration: $E_2^{\#} = [0, +\infty[$

Iteration 1: $E_2^\# = [0, 1000] \Rightarrow \text{stable}$

Consequence: $E_5^{\#} = [1000, 1000]$



Tuning the abstract domains

```
1: n = 0;
2: k = 0;
3: while n < 1000 do
4: n = n + 1;
5: k = k + 1;
6: end
7: exit</pre>
```

• Intervals:

$$E_4^{\#} = \langle n \Rightarrow [0, 1000], k \Rightarrow [0, +\infty[\rangle$$

Convex polyhedra or DBMs:

$$E_4^{\#} = \langle 0 \le n \le 1000, 0 \le k \le 1000, n - k = 0 \rangle$$